

Last lecture: $y''(x) + \underline{A}y'(x) + \underline{B}y(x) = 0$ homogeneous

What if e^{-ax} e^{-bx} most satisfy $a = -b$ $a^2 < 0$

oscillator eqⁿ: $y'' + \omega^2 y = 0 = (D+a)(D+b) = y'' + (A+B)y' + aBy$

ω^2 constant $\in \mathbb{R}$

$A \neq B \neq A \neq B$

$a = -b$ $a^2 < 0 \rightarrow a = \pm i\omega$ 2 solutions

$$(D+i\omega)(D-i\omega)y = (D^2 - i^2\omega^2)y = 0$$

\rightarrow $y_g(t) = \underline{A}e^{i\omega t} + \underline{B}e^{-i\omega t}$
general solution

y is position in Hooke's Law
 $\alpha \neq \beta \in \mathbb{R}$

euler: $e^{\pm i\omega t} = \underline{\cos(\omega t)} \pm i \sin(\omega t)$

$$A = \alpha_r + \alpha_i i$$
$$B = \beta_r + \beta_i i$$

$$y_g(t) = (\alpha_r + \alpha_i i) \cdot (\cos(\omega t) + i \sin(\omega t)) + (\beta_r + \beta_i i) \cdot (\cos(\omega t) - i \sin(\omega t))$$

$$= \underline{\alpha_r \cos(\omega t)} + \underline{\alpha_i i \sin(\omega t)}$$

$$+ \underline{\alpha_i i \cos(\omega t)} + \underline{\alpha_r \sin(\omega t)}$$

$$+ \beta_r \cos(\omega t) - \beta_i i \sin(\omega t)$$

$$+ \beta_i i \cos(\omega t) - \beta_r \sin(\omega t)$$

$$= \alpha_r \cos(\omega t) - \alpha_i \sin(\omega t) + \beta_r \cos(\omega t) + \beta_i \sin(\omega t)$$
$$+ i (\alpha_i \cos(\omega t) + \alpha_r \sin(\omega t) + \beta_i \cos(\omega t) - \beta_r \sin(\omega t))$$

$$= \cos(\omega t) [\alpha_r + \beta_r] + \sin(\omega t) [\beta_i - \alpha_i] + i (\cos(\omega t) [\alpha_i + \beta_i] + \sin(\omega t) [\alpha_r - \beta_r])$$

physics: Need a real solution, so we need $\alpha_i + \beta_i = 0$ & $\alpha_r - \beta_r = 0$ to equal zero

$$\alpha_i + \beta_i = 0$$
$$\rightarrow \alpha_i = -\beta_i$$

$$\alpha_r - \beta_r = 0$$
$$\alpha_r = \beta_r$$

$$A = \alpha_r + \alpha_i i = \beta_r - \beta_i i$$
$$B = \beta_r + \beta_i i = \beta_r + \beta_i i$$

\rightarrow conjugates

$$y_g(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t)$$

initial conditions: $y(0) = C_1$
 $\dot{y}(0) = \omega C_2$

Non homogeneous! 15.1.2

Some 2nd order ODE:

$$a y'' + b y' + c y(x) = f(x)$$

acceleration
damping
restoring force
driving force

say a driven, damped oscillator

we already know homogeneous gets exp() solutions

if $f(x)$ is some exp(), we can expand a Fourier series & add up

if $f(x) = D e^{dx}$

constant
↓

$\exp(\star \cdot x) \rightarrow$ indpt. f^{ns} , noway addup different types exponentials & end up w/ e^{dx} , so need same form need same exponential constant

$$\Rightarrow y(x) = A e^{dx}$$

$$\rightarrow A e^{dx} [a d^2 + b d + c] = D e^{dx}$$

$$A = \frac{D}{a d^2 + b d + c}$$

now know amplitude
 A, D could be complex

Fourier expand for general case: what if $f(x) = D e^{dx} + \Delta e^{\delta x}$

Linear means $\rightarrow y = y_D + y_\Delta = A e^{dx} + B e^{\delta x}$ works

$$A = \frac{D}{a d^2 + b d + c}$$

$$B = \frac{\Delta}{a \delta^2 + b \delta + c}$$

break down to single one component problem

general $y_g(x) = y_p(x) + y_c(x)$

$$a y_c'' + b y_c' + c y_c = 0$$

↓ driving
↓ transient

$$A = \frac{-i D M}{(\omega_0^2 - \omega^2) + i \gamma \omega} \cdot \frac{(\omega_0^2 - \omega^2) - i \gamma \omega}{(\omega_0^2 - \omega^2) - i \gamma \omega} = \frac{D}{M} \cdot \frac{\gamma \omega - i(\omega_0^2 - \omega^2)}{(\omega_0^2 - \omega^2)^2 + \gamma^2 \omega^2}$$

$$\begin{aligned} y_p(t) &= \operatorname{Re}[A e^{i \omega t}] = \operatorname{Re}\left[\frac{D}{M} \cdot \frac{1}{(\omega_0^2 - \omega^2)^2 + \gamma^2 \omega^2} \cdot [\gamma \omega - i(\omega_0^2 - \omega^2)] \cdot e^{i \omega t} \right] \\ &= \frac{D}{M} \cdot \frac{1}{(\omega_0^2 - \omega^2)^2 + \gamma^2 \omega^2} \cdot \operatorname{Re}[\gamma \omega - i(\omega_0^2 - \omega^2)] \cdot e^{i \omega t} \\ &= \dots \cdot \operatorname{Re}[\underbrace{\gamma \omega - i(\omega_0^2 - \omega^2)}_{\text{euler}} \cdot (\cos(\omega t) + i \sin(\omega t))] \\ y_p(t) &= \frac{D}{M} \frac{\gamma \omega \cos(\omega t) + (\omega_0^2 - \omega^2) \sin(\omega t)}{(\omega_0^2 - \omega^2)^2 + \gamma^2 \omega^2} \quad \rightarrow \text{resonance denominator} \end{aligned}$$

$$y_h(t): \quad \ddot{y}_c + \gamma \dot{y}_c + \omega_0^2 y_c = 0 \quad y_c \propto e^{\alpha t}$$

$$(\alpha^2 + \gamma \alpha + \omega_0^2) e^{\alpha t} = 0$$

$$\alpha^2 + \gamma \alpha + \omega_0^2 = 0$$

$$\rightarrow \alpha = -\frac{\gamma}{2} \pm \sqrt{\frac{\gamma^2}{4} - \omega_0^2}$$

for $\gamma \ll \omega_0$

$$y_h(t) = \left[\underline{A_+} e^{i\sqrt{\omega_0^2 - \frac{\gamma^2}{4}} t} + \underline{A_-} e^{-i\sqrt{\omega_0^2 - \frac{\gamma^2}{4}} t} \right] e^{-\frac{\gamma}{2} t}$$

transient term

$$y_g(x) = y_p(t) + \operatorname{Re}[y_h(t)]$$

$$\gamma \omega - i(\omega_0^2 - \omega^2) (\cos(\omega t) + i \sin(\omega t))$$

$$\gamma \omega \cos(\omega t) - i^2 (\omega_0^2 - \omega^2) \sin(\omega t) + \gamma \omega i \sin(\omega t) - i (\omega_0^2 - \omega^2) \cos(\omega t)$$

$$\gamma \omega \cos(\omega t) + (\omega_0^2 - \omega^2) \sin(\omega t) + i [\gamma \omega \sin(\omega t) - (\omega_0^2 - \omega^2) \cos(\omega t)]$$

$$\operatorname{Re}[\dots] = \gamma \omega \cos(\omega t) + (\omega_0^2 - \omega^2) \sin(\omega t)$$