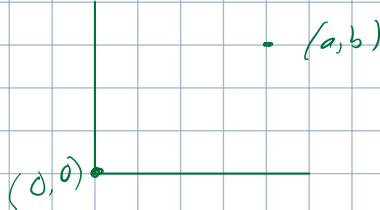


Last time: $\frac{\partial F(y, y', x)}{\partial y} = \frac{d}{dx} \left[\frac{\partial F}{\partial y'} \right]$ or $\frac{\partial F}{\partial x} = \frac{d}{dx} \left[F - y' \frac{\partial F}{\partial y'} \right]$
 no explicit x dependence

if F has no explicit x : $\frac{\partial F}{\partial y} = \text{const.}$

example: distance in 2D



Functional to minimize: $J = \int_{(x,y)}^{(a,b)} ds = \int_0^a \sqrt{1+y'^2} dx$
 $\rightarrow F = \sqrt{1+y'^2}$

$F_{y'} = \text{const.} = \frac{y'}{\sqrt{1+y'^2}} \rightarrow c^2(1+y'^2) = y'^2$
 $\rightarrow c^2 + c^2 y'^2 = y'^2 \rightarrow y'^2(1-c^2) = c^2$
 $y' = \pm \sqrt{\frac{c^2}{1-c^2}} = \text{const.}$
 $y = c_1 x + c_2$

How to do in 3-D?

$y' = \frac{d}{dx} [y(x)]$ $z' = \frac{d}{dx} [z(x)]$

$ds = \sqrt{dx^2 + dy^2 + dz^2} = \sqrt{1 + y'^2 + z'^2} dx$

try same type of derivation as last time

Solⁿs $y(x) = \tilde{y}(x) + \epsilon n_1(x)$ w/ $n_1(a) = n_1(b) = 0$ endpoints
 $z(x) = \tilde{z}(x) + \epsilon n_2(x)$ w/ $n_2(x) = 0$ e endpoints

$\left. \frac{dJ}{d\epsilon} \right|_{\epsilon=0} = \int dx \cdot \frac{d}{d\epsilon} [F] = \int dx \left[\frac{\partial F}{\partial y} \cdot \frac{dy}{d\epsilon} + \frac{\partial F}{\partial y'} \cdot \frac{dy'}{d\epsilon} + \frac{\partial F}{\partial z} \cdot \frac{dz}{d\epsilon} + \frac{\partial F}{\partial z'} \cdot \frac{dz'}{d\epsilon} \right]$

integrate by parts for both n_1, n_2

$0 = \int dx \left[n_1(x) \left(F_y - \frac{d}{dx} [F_{y'}] \right) + n_2(x) \left(F_z - \frac{d}{dx} [F_{z'}] \right) \right]$
 $\rightarrow = 0$ for any n_1, n_2
 have E-L for each

$E-L$ eqⁿ for each dependent variable:

$$\frac{\partial F(y_1, y_1', \dots, y_n, y_n')}{\partial y_i'} = \frac{d}{dx} \left[\frac{\partial F}{\partial y_i'} \right]$$

For 3-D distance: $F = \sqrt{1+y'^2+z'^2}$
no explicit x

$$F_{y_1'} = C_1 = \frac{y_1'}{\sqrt{1+y_1'^2+z_1'^2}}$$

$$F_{z_1'} = C_2 = \frac{z_1'}{\sqrt{1+y_1'^2+z_1'^2}}$$

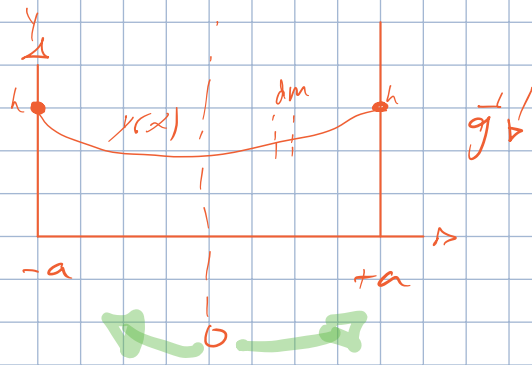
$$\hat{y}(x) = Ax+B$$

$$\hat{z}(x) = Cx+D$$

Constrained Problems

Shape of hanging rope:
(catenary)

constraint: length L



$$ds = \sqrt{1+y'^2} dx$$

constraint: $\int_{-a}^a ds = L$

physics: minimize PE $\cdot dU = dm \cdot g \cdot y(x)$

$$U = \rho \cdot g \cdot \int_{-a}^a dx \sqrt{1+y'^2} \cdot y$$

$\hookrightarrow F(y, y'(x))$

define $G \equiv \sqrt{1+y'^2} - \frac{L}{2a}$ \rightarrow constant $\leq \int_{-a}^a G dx = 0$

\rightarrow adjust functional

$$J \rightarrow \int (F + \lambda G) dx$$

λ - Lagrange multiplier

\tilde{F} - original F w/ constraint

derivative \rightarrow

$$\tilde{F} = \sqrt{1+y'^2} \cdot (y + \lambda)$$

$$\begin{aligned} & y \sqrt{1+y'^2} + \lambda (\sqrt{1+y'^2} - \frac{L}{2a}) \\ & y \sqrt{1+y'^2} + \lambda \sqrt{1+y'^2} - \lambda \frac{L}{2a} \\ & \sqrt{1+y'^2} (y + \lambda) - \lambda \frac{L}{2a} \end{aligned}$$

absorbed by C

no explicit x: $\tilde{F}_x = 0 \rightarrow \tilde{F} - y' \cdot \frac{\partial \tilde{F}}{\partial y'} = \text{const.}$

$$C = \sqrt{1+y'^2} \cdot (y + \lambda) - y' (y + \lambda) \frac{y'}{\sqrt{1+y'^2}} = \frac{y + \lambda}{\sqrt{1+y'^2}} (1 + y'^2 - y'^2)$$

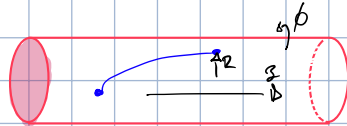
$$c^2 \dot{y}^2 = (y+\lambda)^2 - c^2 \rightarrow \dot{y} = \frac{\sqrt{(y+\lambda)^2 - c^2}}{c^2} \quad \text{separable}$$

$$y+\lambda = C \cosh\left(\frac{x-x_0}{c}\right) \quad u = y+\lambda$$

get constants from $\pm x$ symmetry $\S L$

Another type of example: geodesics

consider constrained on cylinder surface



$$ds = \sqrt{dr^2 + dz^2 + (r d\phi)^2}$$

Choose g to be indpt.

dist. between 2 points

$$F = \sqrt{1 + r'^2 + r^2 \phi'^2} dz$$

but, need to be on surface

constraint: $r=a$ fixed cylinder radius: $G = r-a = 0$
 a (const by $\frac{d}{dz}$)

$$\tilde{F} = \sqrt{1 + r'^2 + r^2 \phi'^2} + \lambda \cdot r$$

E-L eqn: (1) $F_r = \frac{d}{dz} [F_{r'}]$

$r=a \rightarrow r'=0$

$$\lambda + \frac{r \phi'^2}{\sqrt{1+r'^2+r^2\phi'^2}} = 0$$

$$-\lambda = \frac{a \phi'^2}{\sqrt{1+a^2\phi'^2}}$$

(2) $F_\phi = \frac{d}{dz} [F_{\phi'}]$ no explicit ϕ

$$\tilde{F}_\phi = C = \frac{a^2 \phi'}{\sqrt{1+a^2\phi'^2}} \rightarrow \phi' = \pm \frac{c}{a^2(a^2-c^2)} = \text{constant}$$

along z , $d\phi dz$

Note: could have been tricky \S unrolled cylinder

