



empty?

```
bool is_empty(intree_t *t)
return t == null
```

leaf?

```
bool is_leaf(intree_t *t)
return t->left == null && t->right == null
```

get value

```
int get_val(intree_t *t)
assert(!is_empty(t))
return t->val
```

```
intree_t *left(intree_t *t)
assert(!is_empty(t))
return t->left
```

```
intree_t *right(intree_t *t)
assert(!is_empty(t))
return t->right
```

```
bool is_member(intree_t *t, int val)
```

```
if(is_empty(t))
return false
```

```
return t->val == val
```

```
||| is_member(t->left, val)
||| is_member(t->right, val)
```

```
int count(intree_t *t)
```

```
if(is_empty(t))
return 0
```

```
int left = count(t->left)
```

```
int right = count(t->right)
```

```
return left + right + 1
```

```
void free_tree(intree_t *t)
```

```
if (is_empty(t))
    return
```

```
free_tree(t->left)
free_tree(t->right)
```

```
free(t)
```

avoid reaching  
into children tree

```
void get_depth(intree_t *t)
```

```
assert(!is_empty(t))
```

```
if (is_empty(t))
    return 0
```

```
int left_depth = get_depth(t->left)
int right_depth = get_depth(t->right)
```

```
if (left > right)
    return left + 1
else
    return right + 1
```

longest path from root to subtree

depth can be edge or nodes

## Part 2

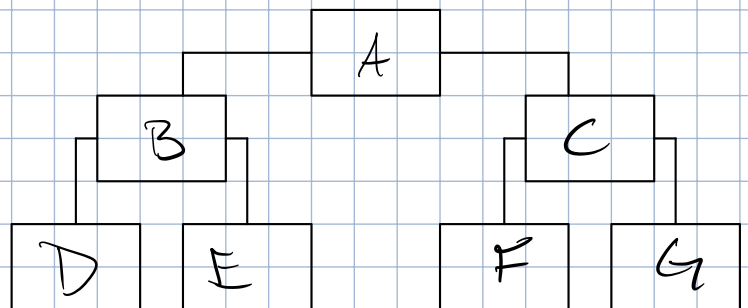
Tree traversal

Depth first: starting from root, visit all nodes in 1 branch

Breadth first: starting from root visit all nodes on current level

Depth

```
preorder  A B D E C F G
in order  D B E A F C G
post order D E B F G C A
```



```
void preorder_print(intree_t *t)
```

```
if (is_empty(t))
    return
printf(t->val)
```

preorder\_print( t -> left )

preorder\_print( t -> right )

right type?  
closer to base case?

void inorder\_print( intree\_t \*t )

if( is\_empty( t ) )  
return

preorder\_print( t -> left )

printf( t -> val )

preorder\_print( t -> right )

void postorder\_print( intree\_t \*t )

if( is\_empty( t ) )  
return

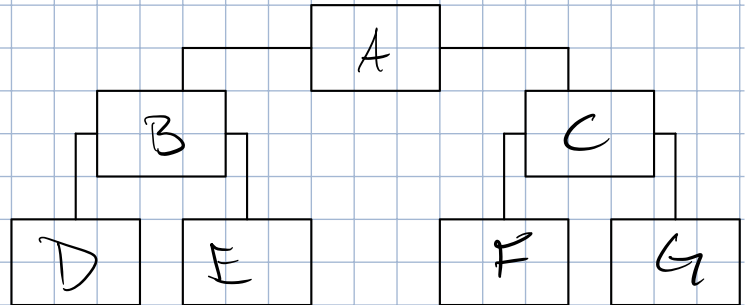
preorder\_print( t -> left )

preorder\_print( t -> right )

printf( t -> val )

Breadth

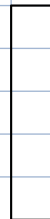
level order: A BCDEFG



lets make a queue!

collection of elements w/limited operations

- ① create empty queue
- ② Enqueue element at back of queue
- ③ Dequeue element at front of queue



typedef struct queue queue\_t

struct queue {  
intlist\_t \*front  
intlist\_t \*back  
}

}

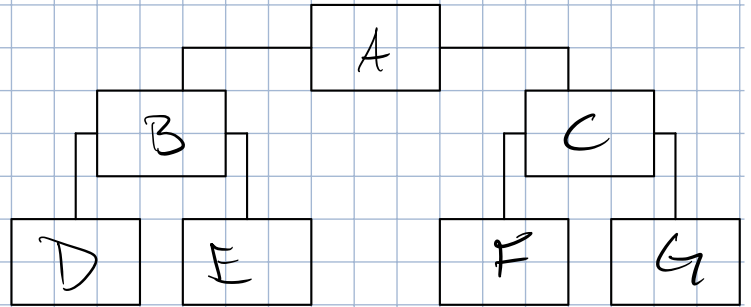
intlist\_t \*newnode  
queue\_t \*create\_queue  
int dequeue

now to implement

instead of a queue w/ int lists, we need one w/ int trees

after printing a tree, we enqueue its children, dequeue that tree

\*  
print \*  
Ⓐ B C  
print B  
Ⓐ Ⓑ C DE



queue\_t \*q = create\_queue();  
int tree\_t \*curr = t

if (is\_empty(t))  
return

printf(curr->val)

if (!is\_empty(curr->left))  
enqueue(q, curr->left)  
if (!is\_empty(curr->right))  
enqueue(q, curr->right)

curr = dequeue(q)

Part 2

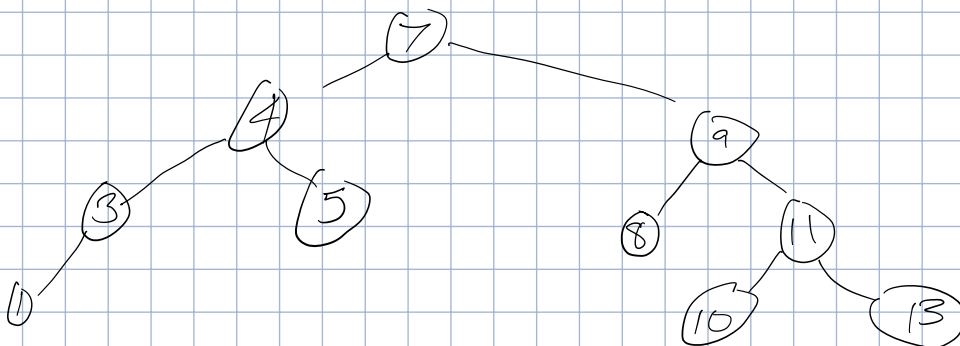
Binary Search Tree (BST)

values are unique

values in left subtree are strictly less than root

values in right subtree are strictly more than root

left & right are BSTs



how do we find if something is in tree?  
can now pick where to go if node  $\neq$  value.

can ask node  $\geq$  value or node  $\leq$  value

bool bst\_lookup (intree\_t \*t, int val)

if (is\_empty(t))  
return false

if (t->val == val)  
return true

if (t->val > val)

return bst\_lookup(t->left, val)

if (t->val < val)

return bst\_lookup(t->right, val)  $\rightarrow$  unnecessary

intree\_t \*insert (intree\_t \*t, int val)

if (is\_empty(t))  
return makenode(val, null, null)

if (t->val > val)  
t->left = insert(t->left, val)

else if (t->val < val)  
t->right = insert(t->right, val)

else  
ayo, this shit already there dawg  
return t

remove value

leaf?  $\rightarrow$  remove it

if value has only 1 child  $\rightarrow$  copy value from child & remove child

if value has 2 children  $\rightarrow$  copy value from in-order successor & delete in-order successor

intree\_t \*remove\_node (intree\_t \*t, int val)

if (is\_empty(t))  
return t

if (t->val > val)

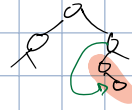
t->left = remove\_node(t->left, val)

```
else if (t->val < val)
    t->right = remove_node(t->left, val)
```

```
else {
```

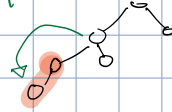
```
if (is_empty(t->left))
    inttree_t *temp = t->right
    free(t)
    return temp
```

only 1 child, right. left is empty



```
if (is_empty(t->right))
    inttree_t *temp = t->left
    free(t)
    return temp
```

only 1 child, left. right is empty



```
inttree_t *temp = min_value(t->right)
t->val = temp->val
t->right = remove_node(t->right, temp->val)
```

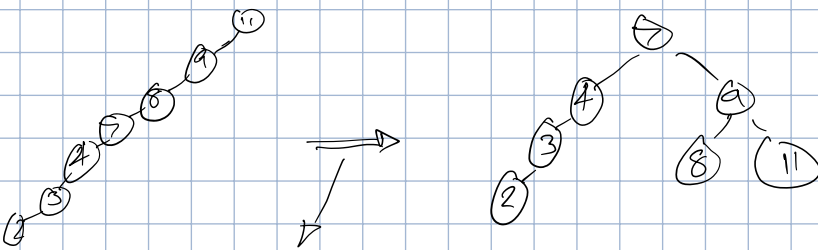
```
}
```

```
return t
```

more

binary search tree (BST) can be unbalanced  $\hookrightarrow$  bad lookup times

vs balanced



In order traversal : 2 3 4 7 8 9 11

```
int count_nodes (inttree_t *t)
```

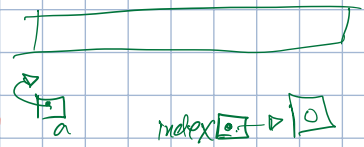
```
if (is_empty(t))
    return 0
```

```
int left = count_nodes(t->left)
int right = count_nodes(t->right)
```

```
return 1 + left + right
```

```
int tree_t *balance(int tree_t *t)
```

```
int count = count_nodes(t)
int *a = (int *) malloc(sizeof(int) * count)
int index = 0
make_array(t, a, &index)
```

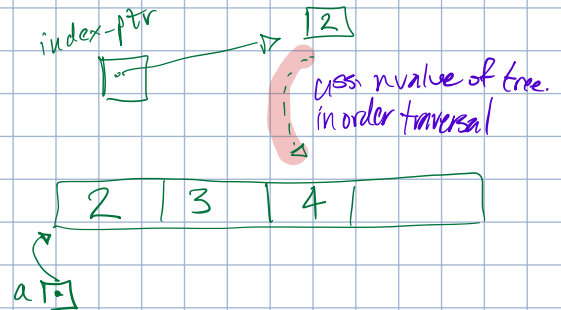


```
return make_bst(a, 0, count-1)
```

```
void make_array(int tree_t *t, int *a, int *index_ptr)
```

```
if (is_empty(t))
    return;
```

```
make_array(t->left, a, index_ptr)
a[*index_ptr] = t->val
*index_ptr += 1
make_array(t->right, a, index_ptr)
```



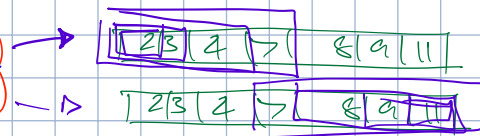
0 count-1

```
int tree_t make_bst(int *a, int start, int end)
```

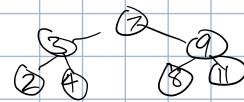
```
if (start > end)
    return null
```

```
int middle = (start+end)/2
int tree_t *t = make_node(a[middle], null, null)
```

```
t->left = make_bst(a, start, middle-1)
t->right = make_bst(a, middle+1, end)
```



```
return t
```



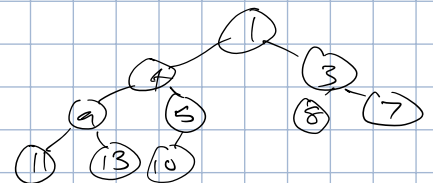
full binary tree: all nodes not a leaf has 2 children

complete binary tree: all levels (except maybe last) filled & all nodes in last level are left justified

Min heaps: binary tree

complete  
unique values

values in left & right subtrees strictly greater than root  
left & right subtrees are min heaps





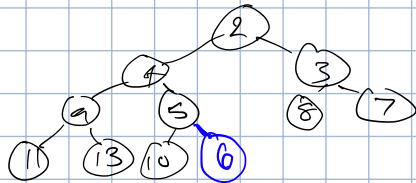
max heap

complete  
unique values

values in left & right subtrees strictly less than root  
left & right subtrees are min heaps

cod operations: add min heaps remove min, is empty

let's add 6



bool \*is\_heap(int root \*t)

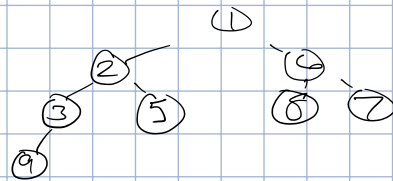
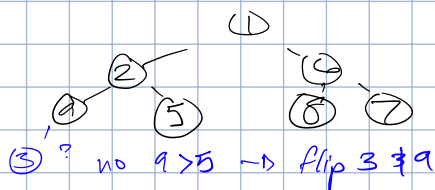
if (isleaf(t))  
return true

if (is-empty(t->right))  
return (t->left->val) > (t->val) no right kids, only need to check left value

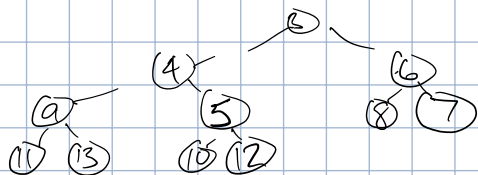
if ((t->left->val) > (t->val) && (t->right->val) > (t->val))  
return is\_heap(t->left) && is\_heap(t->right)

return false

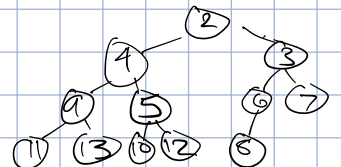
add 3



add 2



sift up until we have a heap



put into next open slot



```
void insert(int heap[], int size, int index)
```

```
*size = *size + 1
```

```
heap[*size - 1] = val
```

```
sift_up(heap, *size - 1)
```

insert @ end of array  
sift that up

```
void sift_down(int heap[], int size, int index)
```

make sure we got space in heap

```
int min_index = index
```

```
int left = 2 * index + 1
```

```
int right = 2 * index + 2
```

```
if (left < size)
```

```
if (heap[left] < heap[min_index])
```

```
min_index = left
```

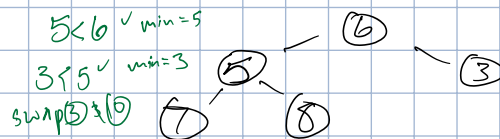
```
if (right < size)
```

```
if (heap[right] < heap[min_index])
```

```
min_index = right
```

② in earlier example

```
if (min_index != index)
```



```
void remove_min(int heap[], int *size)
```

```
int last = heap[*size - 1]
```

```
heap[0] = last
```

```
*size = *size - 1
```

```
sift_down(heap, *size, 0)
```

```
void build_heap
```

```
for (int i = size/2; i >= 0; i--)
```

```
sift_down(a, size, i)
```

more heaps

```
void heap_sort(int heap[], int size)
```

```
for (int i = size - 1; i > 0; i--)
```

```
swap(&heap[0], &heap[i])
```

```
sift_down(heap, i, 0)
```

priority queue: queue with...

every element has priority

elements w/ high priority dequeued before elements w/ lower priority

...

dictionaries: maps key to values  
↳ unique

set: store collection of unique values

how to implement?

linked lists!

easy

but lookup is time proportional to length of list

but adding key-value pairs takes time proportional length of list

binary search tree!

easy

adding values is pretty good

but lookup time is proportional to height of tree

hash tables!

hash tables!

goal: add, remove, query in near constant time

idea: trade space for time

$A[key] = \text{item}$

space of array?

need slot for each possible value key could take

what if keys are integers? strings?

may need array larger than memory of computer

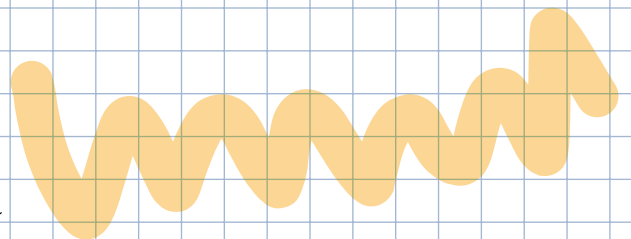
only need array large enough to hold max number of items stored at same time

$A[\text{hash}(key)] = \text{item}$

$\text{hash}(key_1) \neq \text{hash}(key_2)$  if  $key_1 \neq key_2$

$0 \leq \text{hash}(key) < N$   $\rightarrow$  array length

collisions can happen w/ rare occurrence



Suppose we have 1000 spots in  $A$

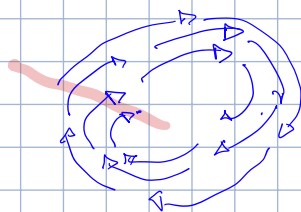
$$\text{hash}(\text{key}) = \text{key} \% 1000$$

nice if uniformly distributed

String keys  $\sim 1000 \leq \text{spots}$

hash code should depend on entire input key  
output should look "random"

```
int hash( char *s )  
int h = 0  
while( *s )  
    h = h * 37 + int( *s++ )  
h = h % HASH_SIZE
```



2 handles of collisions

linear probing: put item in next available slot if original slot is occupied

separate chaining: keep list of items in each slot

0	1	2	3	4	5	6	7	8	9
B	C	X	W	Y	Z	D	E	F	A

```
insert W: hash( W ) → 3  
          hash( X ) → 2  
          hash( Y ) → 4  
          hash( Z ) → 2  
          3? 4? 5? ✓
```

```
lookup Z: hash( Z ) → 2  
          3? 4? 5? ✓
```

```
lookup H: hash( H ) → 2  
          3? 4? 5? 6? X → H is not in hashtable
```

```
insert A: hash( A ) → 9  
          hash( B ) → 9  
          0 add 1 & mod(size) → 0? ✓
```

insert rest:

```
insert G: hash( G ) → 6  
          infinite loop! grows array or if we get back to 6, say not there
```

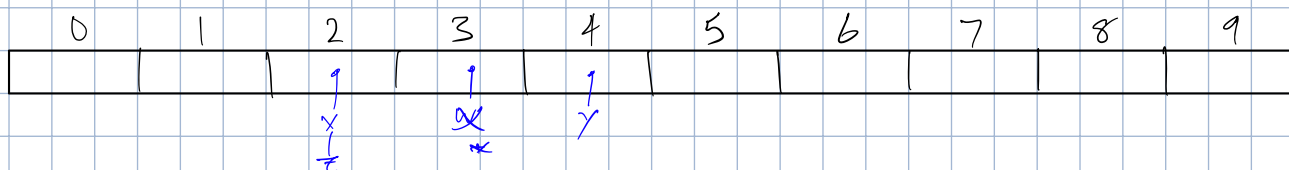
remove W:  $\text{hash}(W) \rightarrow 3$

but now can't find Z!  
don't remove, mark is dead !

limit collisions  
move on lookup  
re-hash

## More hash tables

separate chaining  $\rightarrow$  buckets



insert W:  $\text{hash}(W) \rightarrow 3$   
 $\text{hash}(Y) \rightarrow 4$   
 $\text{hash}(X) \rightarrow 2$   
 $\text{hash}(Z) \rightarrow 2$

lookup F:  $\text{lookup}(F) \rightarrow 2$

F is not X or Z, either in bucket 2 or not

remove W:  $\text{hash}(W) \rightarrow 3$

take out W & put asterisk bucket. don't need tombstone

how to implement bucket? linked list

long bucket? use good hash fn

rehashing:

define load factor as avg num of entries per slot

if it reaches specified threshold, create larger table, hash all data into it, replace current

bonus option: keep old table for while, gradually move items to new table

## Graphs!

graphs have vertices, nodes representing entities

graphs have edges to represent relationships between 2 vertices

types

directed - links go oneway, not reciprocated  
undirected - all edges go both ways

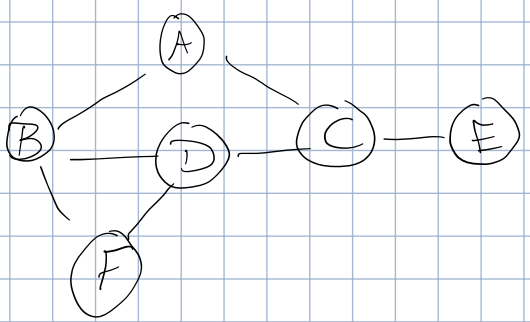
source → sink

weighted - each edge has weight signaling strength of relationship  
unweighted - relationship strengths are equal

researchers co-authored at least 1 paper  
undirected  
can be weighted by # of papers

adjacency matrix

let's have an  $N \times N$  matrix

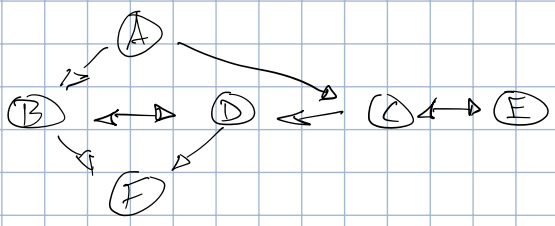


	A	B	C	D	E	F
A	0	1	1	0	0	0
B	1	0	0	1	0	1
C	1	0	0	1	1	0
D	0	1	1	0	0	1
E	0	0	1	0	0	0
F	0	1	0	1	0	0

table is symmetric

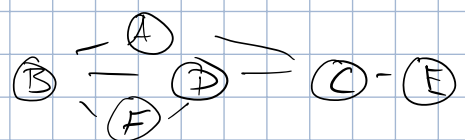
if it weighted, put value  $w$

if directed, it is not symmetric



	A	B	C	D	E	F
A						
B						
C				1	0	
D	0	1	0	0	0	1
E						
F						

Adjacency list



- list
- A: B, C
  - B: A, D, F
  - C: A, D, E
  - D: B, C, F

E: C  
F: B, D

for weighted, have tuples?

A: (B, 2), (C, 1)