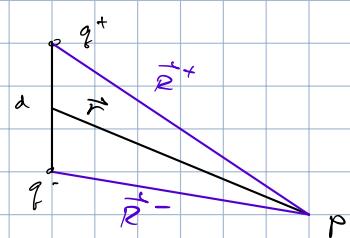


$$\Phi(\vec{r}, t) = \left(\frac{q_0}{4\pi\epsilon_0} \right) \left(\frac{\cos[\omega(t - \frac{r}{c})]}{R_+} - \frac{\cos[\omega(t - \frac{r}{c})]}{R_-} \right)$$



$$R_{\pm} = r^2 + rd\cos\theta + \left(\frac{d}{2}\right)^2$$

$$\frac{1}{R_{\pm}^2} \approx \frac{1}{r^2} \left(1 + \frac{d}{2r} \cos\theta \right)$$

$$\cos[\omega(t - \frac{r}{c})] \rightarrow \cos \left[\underbrace{\omega(t - \frac{r}{c})}_{\equiv \alpha} \pm \underbrace{\frac{\omega d}{2c} \cos\theta}_{\equiv \beta} \right]$$

$$\cos[\omega(t - \frac{r}{c})] \approx \cos\alpha \cos\beta + \sin\alpha \sin\beta$$

using $\left(\frac{\omega d}{2c}\right) \ll 1$, $\beta \rightarrow 0$ & $\cos\beta \rightarrow 1$ & $\sin\beta \rightarrow \beta$

$$\cos[\omega(t - \frac{r}{c})] \approx \cos\alpha + \beta \sin\alpha$$

$$\begin{aligned} \Phi(\vec{r}, \theta, t) &= \left(\frac{q_0}{4\pi\epsilon_0} \right) \left(\frac{1}{r} \right) \left\{ (\cos\alpha - \beta \sin\alpha) \left(\frac{d}{2r} \cos\theta + 1 \right) + (\cos\alpha + \beta \sin\alpha) \left(\frac{d}{2r} \cos\theta \right) \right\} \\ &= \left(\frac{q_0}{4\pi\epsilon_0} \right) \left(\frac{1}{r} \right) \cdot \left(\frac{d}{r} \cos\alpha \cos\theta - 2\beta \sin\alpha \right) \\ &= \left(\frac{q_0}{4\pi\epsilon_0} \right) \cdot \left(\frac{d \cos\theta}{r} \right) \left(\frac{\cos\alpha}{r} - \frac{\omega}{c} \sin\alpha \right) \quad \alpha = \omega(t - \frac{r}{c}) \end{aligned}$$

factor out a $\frac{1}{r}$, $\frac{\omega}{c} \gg 1$ by radiation $\rightarrow \sin$ dominates

$$\Phi(\vec{r}, \theta, t) = \left(\frac{q_0}{4\pi\epsilon_0} \right) \cdot \left(\frac{\omega}{c} \right) \cdot \left(\frac{\cos\theta}{r} \right) \cdot \sin[\omega(t - \frac{r}{c})]$$

vector potential: $\vec{A}(t) = \frac{d\vec{a}(t)}{dt} \hat{j} = -q_0 \omega \sin(\omega t) \hat{j}$

$$\vec{A}(\vec{r}, t) = \frac{q_0}{4\pi} \int_{-d/2}^{d/2} -\frac{q_0 \omega \sin(\omega t)}{R_{\pm}} \hat{j}$$

$$= -\frac{\mu_0 \rho_0 \omega}{4\pi r} \sin(\omega t_r) \hat{j}$$

$$\vec{A}(\vec{r}, \theta, t) = -\left(\frac{\mu_0 \rho_0 \omega}{4\pi r} \right) \sin[\omega(t - \frac{r}{c})] (\cos\theta \hat{i} + \sin\theta \hat{j})$$

$$\vec{E}(\vec{r}, \theta, t) = -\left(\frac{\mu_0 p_0 \omega^2}{4\pi}\right) \cdot \left(\frac{\sin\theta}{r}\right) \cos(\omega t_r) \hat{\theta}$$

$$\vec{B}(\vec{r}, \theta, t) = -\left(\frac{\mu_0 p_0 \omega^2}{4\pi c}\right) \cdot \left(\frac{\sin\theta}{r}\right) \cos(\omega t_r) \hat{\phi}$$

$$\vec{S} = \frac{1}{\mu_0} [\vec{E} \times \vec{B}] = \frac{\mu_0}{c} \left[\left(\frac{p_0 \omega^2}{4\pi}\right) \left(\frac{\sin\theta}{r}\right) \cos(\omega t_r) \right]^2 \hat{r}$$

$$\langle S \rangle = \left(\frac{\mu_0 p_0^2 \omega^4}{32\pi^2 c} \right) \cdot \underbrace{\left(\frac{\sin^2\theta}{r^2} \right)}_{\text{sync } f^e}$$

$$\langle P \rangle = \frac{\mu_0 p_0^2 \omega^4}{12\pi c}$$