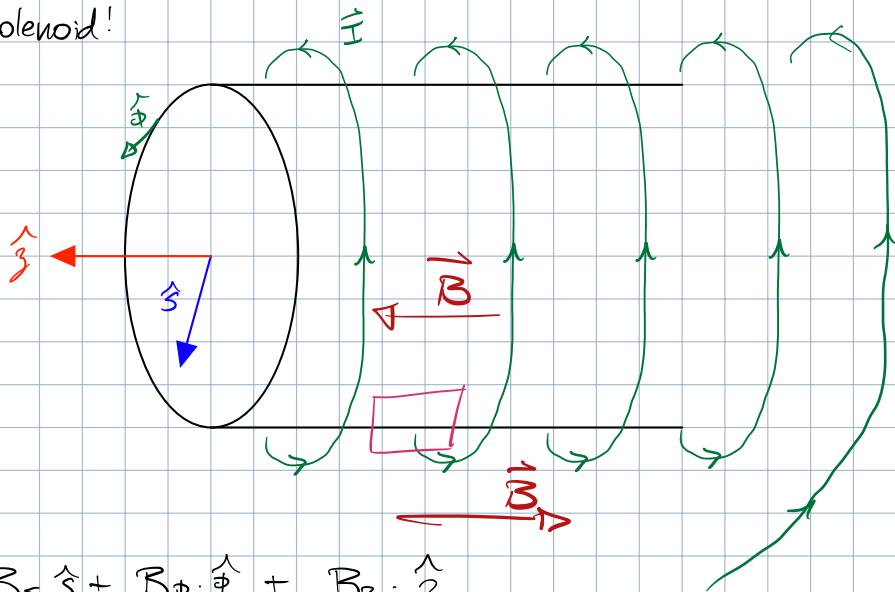
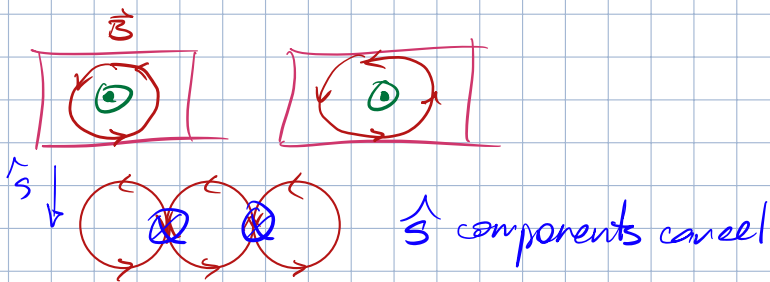


Example: Solenoid!



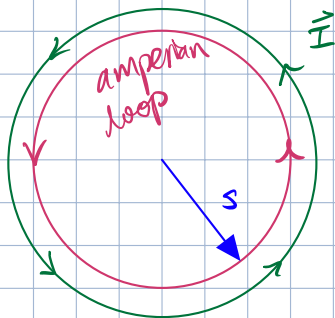
$$\vec{B} = B_s \hat{s} + B_\phi \hat{\phi} + B_z \hat{z}$$

$B_s = ???$



$$B_s = 0$$

$B_\phi = ???$

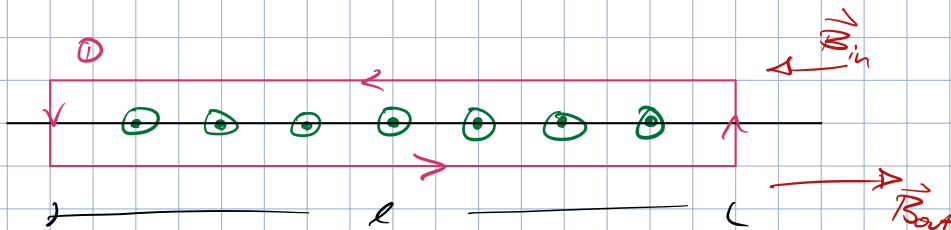


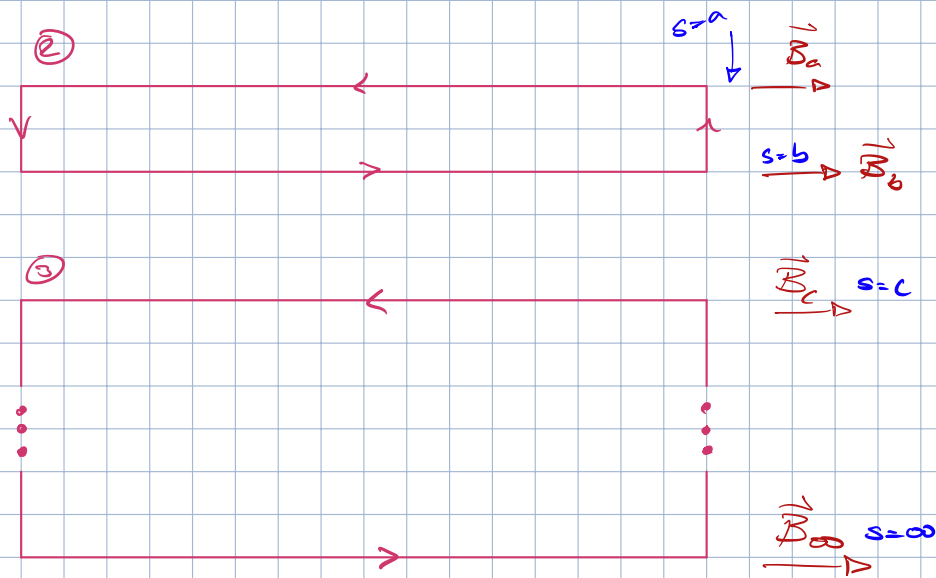
$$\begin{aligned} \oint \vec{B} \cdot d\vec{l} &= \oint \vec{B} \cdot d\vec{l} \hat{\phi} \\ &= \oint B_\phi \cdot dl \quad \left. \begin{array}{l} \text{ } \\ \text{ } \end{array} \right\} \phi \text{ symmetry} \\ &= B_\phi \oint dl \\ &= B_\phi 2\pi s = \mu_0 I_{\text{enc.}} \end{aligned}$$

$\rightarrow 0$

$$\rightarrow B_\phi = 0$$

$B_z = ???$





① $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} = B_{in} \cdot l + B_{out} \cdot l = \mu_0 n l I$ $n = \# \text{ of circles / length}$
 $\star B_{in} + B_{out} = \mu_0 n I$

② $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} = B_b \cdot l - B_c \cdot l = 0$ $I_{enc} = 0$
 $\rightarrow B_a = B_b$

$\rightarrow B_{out}$ is same everywhere outside

③ $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} = -B_c \cdot l = 0$ $I_{enc} = 0$
 $\rightarrow B_c = 0$

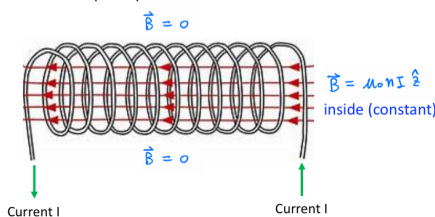
$B_c = B_b = B_a = B_{out}$

$\star \rightarrow B_{in} = B = \mu_0 n I$

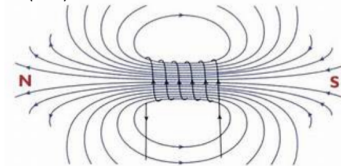
outside: $\vec{B} = 0$

inside: $\vec{B} = \mu_0 n I \hat{z}$
 (constant)

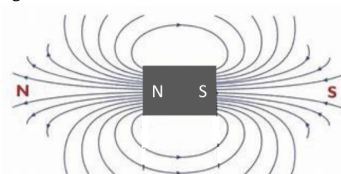
Solenoid (ideal)



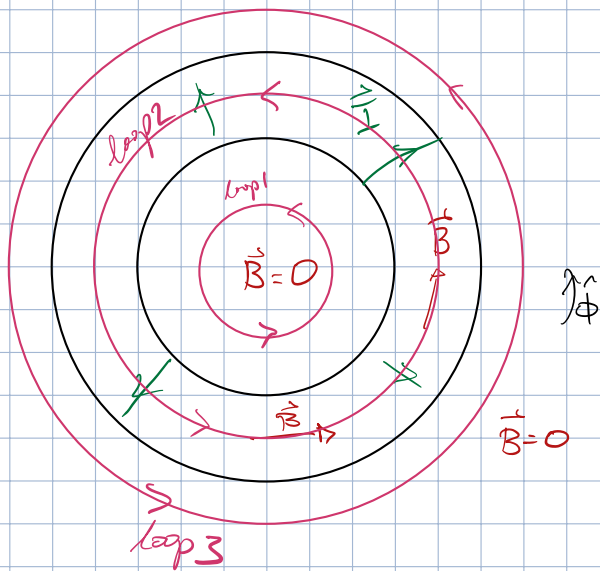
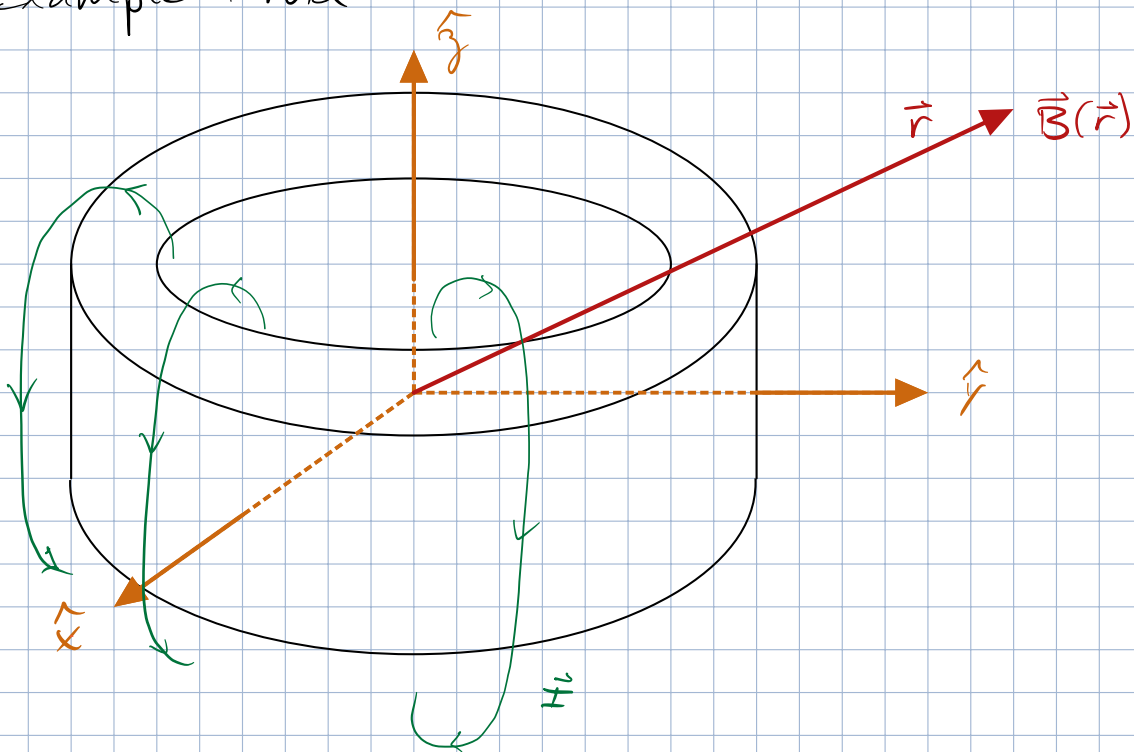
Solenoid (real)



Bar Magnet



Example: Toroid



N total turns

$$\vec{B} = B \hat{\phi}$$

$$B_z = 0$$

$$B_x = 0$$

due to ϕ symmetry, B isn't fⁿ of ϕ

Amperean loops

$$d\vec{l} = s \cdot d\phi \cdot \hat{\phi}$$

$$\vec{B} = B \hat{\phi}$$

for all 3 loops: $\oint \vec{B} \cdot d\vec{l} = 2\pi s B = \mu_0 I_{enc}$

loop 1: $I_{enc} = 0$

loop 2: $I_{enc} = N \cdot I$

loop 3: $I_{enc} = 0$

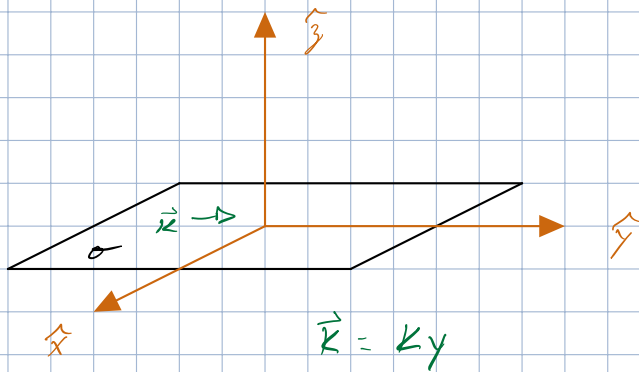
$\rightarrow B_1 = 0$

$\rightarrow B_2 = \frac{\mu_0 I N}{2\pi} \cdot \frac{1}{s}$

$\rightarrow B_3 = 0$

$$\begin{aligned} B_1 &= 0 \\ B_2 &= \frac{\mu_0 I N}{2\pi} \cdot \frac{1}{s} \hat{\phi} \\ B_3 &= 0 \end{aligned}$$

Example: Infinite Surface

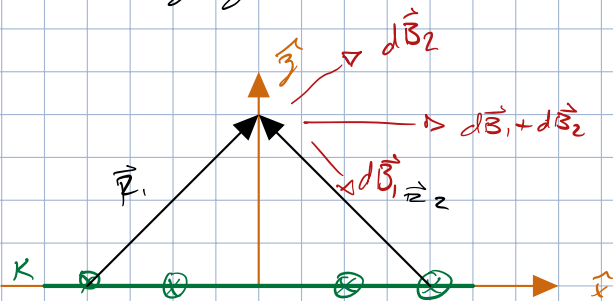


$$\vec{B} = B_x \hat{x} + B_y \hat{y} + B_z \hat{z}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{k} \times \vec{B}}{r^2} da' = \frac{\mu_0}{4\pi} \vec{k} \times \int \frac{\vec{B}}{r^2} da'$$

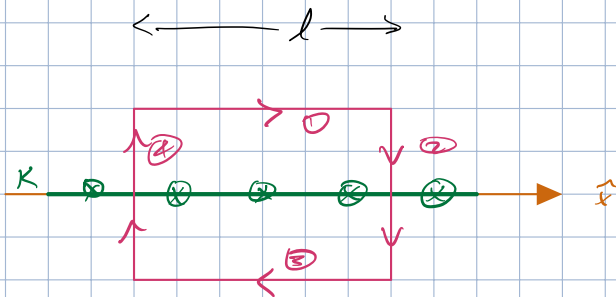
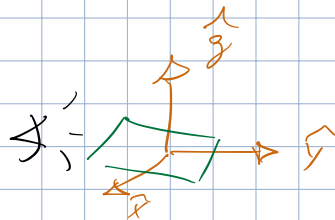
$$\vec{B} \perp \vec{k} \text{ are } \perp \rightarrow \vec{B} \perp \vec{k} \rightarrow B_y = 0$$

$$\vec{B} = B_x \hat{x} + B_z \hat{z}$$



B_z components cancel: $B_z = 0$

$$\vec{B} = B \hat{x}$$



$$\begin{aligned} dl_1 &= dx \cdot \hat{x} &= dx \hat{x} \\ dl_2 &= dz \cdot (-\hat{z}) &= -dz \hat{z} \\ dl_3 &= dx \cdot (-\hat{x}) &= -dx \hat{x} \\ dl_4 &= dz \cdot \hat{z} &= dz \hat{z} \end{aligned}$$

$$\vec{B} = B \hat{x}$$

$$\oint \vec{B} \cdot d\vec{l} \rightarrow \vec{B} \cdot dl_2 = \vec{B} \cdot dl_4 = 0$$

$$\hat{x} \cdot (-\hat{z}) \quad \hat{x} \cdot \hat{z}$$

$$\oint \vec{B} \cdot d\vec{l} = B \oint \hat{x} \cdot d\vec{l} = B_1 \int \hat{x} dx \cdot \hat{x} - B_3 \int \hat{x} dx \cdot \hat{x}$$

$$= B_1 \int dx - B_3 \int dx = B_1 \cdot l - B_3 \cdot l = l(B_1 - B_3)$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} = \mu_0 \cdot K l$$

$$\rightarrow l(B_1 - B_3) = \mu_0 K l$$

$$B_1 - B_3 = \mu_0 K$$

by symmetry, $|B_1| = |B_3| \rightarrow B_3 = -B_1$,

$$\rightarrow 2B_1 = \mu_0 K \rightarrow B_1 = \frac{1}{2} \mu_0 K$$

